# IMPROVING SOFT REAL-TIME PERFORMANCE THROUGH BETTER SLACK RECLAIMING AUTHORS: CAIXUE LIN AND SCOTT A.BRANDT Presenter: Muhammad Ali Awan PhD Student, Cister-ISEP, Portugal.

# OUTLINE

- Motivation
- Slack
- When to allocate slack
- Task selection to allocate slack
- Borrowing from the future
- Donating to the past
- Results
- Conclusion

# MOTIVATION

#### • Application with variety of timing constraints

- Hard real time
- Soft real time
- Best Effort
- Performance Guarantee
  - Worst case resource reservation
  - Average case resource reservation
- Effective Distribution of slack

## WHAT IS SLACK

# • The execution time not used in system is called slack.



#### WHEN TO ALLOCATE SLACK

- Allocate When Real Time(RT) task are idle
  - Isolates RT tasks
  - Delays slack use
- Task Set, T(E,T)
  - T1(1.5,6), .5 unit overrun
  - T<sub>2</sub>(4,8), needs 2 unit
  - T<sub>3</sub>(2.5,10)



#### WHEN TO ALLOCATE SLACK

#### Principle 1:

Allocate slack as early as possible, with the priority of the donating task.

### • SRAND implements principle 1

- On task completion, remaining budget is allocated to randomly selected task
- Fewer deadline misses
- Random selection is not optimal

#### TASK SELECTION TO ALLOCATE SLACK

- Allocate to only overrun task.
- No overrun task at the time of slack generation

• Task Set

- T1(1.5,6), needs 1 unit
- T<sub>2</sub>(4,8), .5 unit overrun
- T<sub>3</sub>(2.5,10)



## TASK SELECTION TO ALLOCATE SLACK

#### Principle 2:

#### Allocate slack to the task with the highest priority (earliest deadline(ED)).

• SLAD Implements principle 1 and 2.

- Make available as soon as possible(principle 1)
- Give it pre-emptively to Earliest Deadline task(principle 2)
- Task consumes slack first, before its reservation
- Interrupting higher priority task consumes leftover slack

• Reasons

- ED task is the Most critical task
- Least likely to receive slack
- Mostly likely to overrun

#### • SLAD outperforms SRAND and CBS

- CBS, RBED, IRIS and BEBS
  - allocate from future if overrun
  - Extend the deadline
- SLAD
  - Allows future borrowing (no slack available)
- o Taskset
  - T1(1.5,3),
    - J1 needs 2 units and J2 needs 1 unit
  - T2(1,8),
  - T3(3,8)



#### Principle 3

Allow tasks to borrow against their own future resource reservations (with the priority of the job from which the resources are borrowed) to complete their current job.

## • SLASH implements principle 1, 2 and 3

- Allows donation as soon as possible, to earliest deadline task (principle 1 and 2)
- Allows borrowing from future job releases
  Similar to (CBS, RBED, IRIS and BEBS)
- In this way it serve the most critical jobs first
- Assumes borrowed resources will turn out to be slack
- Issue with principle 3
  - Overrun task misses opportunity to get slack donation(priority lowered)

Revised Principle 2 Allocate slack to the task with the highest priority (earliest original deadline)

#### DONATING TO THE PAST

#### o Issue

- Finished job with borrowed budget from future
- No longer in the ready queue
- Taskset
  - T1(1.5,3),
    J1 and J2needs 2 units
  - T2(1,8), needs 0.5 units<sub>12</sub>
  - T<sub>3</sub>(3,8)



#### DONATING TO THE PAST

#### Principle 4:

#### Retroactively allocate slack to tasks that have borrowed from their current budget to complete a previous job.

#### • BACKSLASH Implements principle 1,2,3 and 4

- Similar to HistroyReWriting paper for fixed priorities(Static Rate monotonic)
- Task that previously consumed slack are eligible to receive future slack donations

#### • Need to store

- information of the completed jobs that borrowed Depleting jobs
- Outperforms over all other algorithms (SRAND, SLAD and SLASH)

# RESULTS

#### • Metrics

- Deadline Miss Ratio
  - (deadline misses /Number of jobs)
- Tardiness
  - (Total accumulated lateness/Total length of All Periods)
- Fixed task sets
- Random Task set

# FIXED TASK SET (PERFORMANCE AS FUNCTION OF SYSTEM LOAD)

# Table 1. Workload 1

Task	Task		Server			Parameter	
	Parameters		Parameters			Adjustment	
	$e = f(\overline{e})$	р	$B = \overline{e}$	P = p	$U = \frac{B}{P}$	$\Delta(\overline{e})$	$\Delta(U)$
HRT1	258	600	258	600	43%	+12	+2%
HRT2	NW(175)	350	175	350	50%	-14	-4%
SRT3	NA(15)	300	15	300	5%	+6	+2%

# DEADLINE MISS RATIO AS FUNCTION OF LOAD



#### TARDINESS AS FUNCTION OF LOAD



### FIXED TASK SET (PERFORMANCE AS A FUNCTION OF PERIOD)

# Table 2. Workload 2

Task	Task		Server			Parameter	
	Parameters		Parameters			Adjustment	
	$e = f(\overline{e})$	р	В	P	$U = \frac{B}{P}$	$\Delta(\overline{e})$	$\Delta(p)$
HRT1	NW(20)	200	20	200	10%	0	0
HRT2	NW(30)	300	30	300	10%	0	0
HRT3	NW(40)	400	40	400	10%	0	0
HRT4	NW(50)	500	50	500	10%	0	0
HRT5	NW(48)	600	48	600	8%	0	0
SRT6	NA(30)	60	30	60	50%	+20	+40

# DEADLINE MISS RATIO AS A FUNCTION OF PERIOD



#### TARDINESS AS A FUNCTION OF PERIOD



## RANDOM TASK SET

• Variation

- Number of Hard real time task
- Number of soft real time task
- Task model (periodic, aperiodic)
- Task Parameters (1ms to 1000ms)
  - Periods
  - Execution time

#### • Selected random workload

- 12 task sets
  - Each with 8 periodic/aperiodic (random distribution among soft and hard RT tasks)

22



(a) Deadline miss ratio: periodic task sets

23



(b) Tardiness: periodic task sets

24



(c) Deadline miss ratio: aperiodic task sets



(d) Tardiness: aperiodic task sets

# CONCLUSION

## • 4 principle

- As early as possible
- Allocate to earliest deadline first
- Borrow from future
- Retroactively allocate slack
- Implemented the principles in four algorithms
  - SRAND, SLAD, SLASH and BACKSLASH
- BACKSLASH outperform all other algorithms, including CBS, CASH, RBED and IRIS

## REFERENCES

- All material and figures are taken from the original paper(Improving Soft Real-Time Performance Through Better Slack Reclaiming).
- Slack slide is extracted from the SMARTS(Slack MAnagement for hierarchical Real-Time Systems) project proposal.

